EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	506723	(steroscopic or 3D or three adJ dimensional$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:16
L2	4794	L1 and optical adj axis and (left and right)and(camera or ccd or detector$3 or sensor$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:22
L3	2500	L2 and @ad<"20010910"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:31
L4	2500	L3 and optical adj axis and (left and right)and(camera or ccd or detector$3 or sensor$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:47
L5	2012	L4 and optical adj axis and (left and right)and(camera or ccd or detector$3 or sensor$1)and(compar$5 or match$3 or combin$4)and distances	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:26
L6	315	L4 and calculating and(decision or evaluat$3 or jude$3)and (left and right)and(camera or ccd or detector$3 or sensor$1)and(disparity or range or intensity or depth)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:48
L7	296	L5 and calculating and(decision or evaluat$3 or jude$3)and (left and right)and(camera or ccd or detector$3 or sensor$1)and(disparity or range or intensity or depth)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:32
L8	103	L7 and outputt$3 and(disparity or range or intensity or depth)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:30
L9	42	L8 and outputt$3 and(disparity or range or intensity or depth) same(decision or evaluat$3 or jude$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:31

L10	42	L9 and @ad<"20010910"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:49
L11	8	L10 and alternately and storing and(decision or evaluat$3 or jude$3)and(memory or storage or LUT)and (first and second)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:52
L12	4794	L1 and optical adj axis and (left and right)and(camera or ccd or detector$3 or sensor$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:48
L13	27	L1 and calculating and(decision or evaluat$3 or jude$3)same(left and right)same(camera or ccd or detector$3 or sensor$1)same(disparity or range or intensity or depth)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:50
L14	9	L13 and @ad<"20010910"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:50
L15	0	L14 and calculating and(decision or evaluat$3 or jude$3)same(left and right)same(camera or ccd or detector$3 or sensor$1)same outputting same(disparity or range or intensity or depth)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:51
L16	0	L14 and alternately and storing and(decision or evaluat$3 or jude$3)and(memory or storage or LUT)and(first and second)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/06 15:52